Sort Statements
Reference Manual

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HOW TO USE THIS MANUAL

The Sort statements provide programmable, high-speed data sorting, searching, and moving capability to the Wang system. This manual describes the syntax and use of the Sort Statements of the BASIC instruction set. The Sort statement sets for the 2200VP/MVP and 2200VS CPU's are described in separate manuals.

It is assumed that the reader is familiar with the operation of the available system and has a working knowledge of the Wang BASIC language, or has access to Wang reference literature (e.g., the Wang BASIC Language Reference Manual, the Programming in BASIC Manual, the Disk Reference Manual, etc). A general knowledge of data processing techniques is also helpful.

Chapter 1 contains an overview of array fundamentals. Chapter 2 discusses each Sort statement in detail. It is recommended that novice programmers rely upon the Wang-supported sorting utilities rather than programming with the Sort statements. Users who wish to sort disk data files can refer to the ISS (Integrated Support System) sorting routines. Under certain conditions, a user may not need to prepare sorted files, but merely produce lists of sorted data. Another Wang-supported utility, KFAM (acronym for Keyed File Access Method), provides this capability. (See the KFAM Reference Manuals).
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CHAPTER 1 GENERAL INFORMATION

1.1 INTRODUCTION

The six Sort statements can be separated into two categories: those which are used in specific phases of a data-sorting program to reduce both the sort time and program size (MAT CONVERT, MAT SORT, MAT MOVE, MAT MERGE), and those which are generally useful in many text-editing, statistical and random access data retrieval applications to move or search character or data strings (MAT COPY and MAT SEARCH).

The Sort statements presented in this manual are:

**MAT CONVERT** Reformats data from the internal numeric storage format into a hexadecimal sort format and stores it in an alphanumeric array.

**MAT COPY** Copies data byte-by-byte from all or part of one alphanumeric array to all or part of another. Element boundaries are ignored and the data can be copied in forward or reverse directions.

**MAT MERGE** Creates the locator-array used to merge more than one sorted file into a single sorted array or file.

**MAT MOVE** Moves data from an alphanumeric input array to specified locations in an alphanumeric output array. The order of transfer is specified by a locator-array which contains the subscripts of the elements to be moved. Elements can be moved element-by-element, or by fields within each element.

**MAT SEARCH** Searches an alphanumeric array for character strings that satisfy a given relationship. Element boundaries are ignored. The search can be performed at specified intervals and a variable number of characters can be compared.

**MAT SORT** Sorts the elements of an alphanumeric array into ascending or descending order. Puts the subscripts of the ordered data in an output locator-array.
Since it is impossible to discuss all the sorting and merging techniques invented, examples have been chosen to illustrate sorting and the rules, syntax, and use of the Sort statements. The subscript locator-arrays (which are automatically created by MAT MERGE, MAT SEARCH and MAT SORT) are a means to access data by pointing to its location instead of moving it. Compared to the usual sort-and-exchange or bubble sort techniques, the ease of use, rapidity, and efficiency in memory utilization of "tag-sorting" mode excels. These features enhance the Wang system's ability to process applications where rapid access to large amounts of data is desirable, as in statistical analysis where it may be necessary to pass several times over the same mass of data and cull out information according to several parameters without dumping all the data each time. Using a BASIC program, it is fast and simple to read in an array, execute MAT SORT to order all elements in the array, and then execute MAT MOVE to place all the elements in the correct order on an output device.

1.2 INSTALLATION

The Sort statements contained in this manual are standard instructions in the BASIC language instruction set available on all Wang 2200T series CPU's (including WCS, PCS, and Work Stations). The Sort statements can usually be installed as an option in those Wang Series 2200 CPU's not already containing them.

1.3 ARRAYS

This section briefly describes the properties of arrays to assist the user of the Sort statements. Users already familiar with arrays and array notation can skip this section.

An array is a series of elements arranged in a specified order. Arrays can be either one- or two-dimensional. A one-dimensional array can be either a single row or a single column. A two-dimensional array is arranged in rows and columns. Because of this arrangement, the position of each element can be uniquely identified with subscripts. A one-dimensional array (also called a vector) has a single subscript. A two-dimensional array has two subscripts which always represent "row, column", never "column, row". A two-dimensional array resembles a table (see Figure 1-1 and Figure 1-2).

```
<table>
<thead>
<tr>
<th></th>
<th>r</th>
<th>r</th>
<th>r</th>
</tr>
</thead>
<tbody>
<tr>
<td>r</td>
<td>1,1</td>
<td>1,2</td>
<td>1,3</td>
</tr>
<tr>
<td>r</td>
<td>2,1</td>
<td>2,2</td>
<td>2,3</td>
</tr>
<tr>
<td>r</td>
<td>3,1</td>
<td>3,2</td>
<td>3,3</td>
</tr>
</tbody>
</table>
```

Figure 1-1. A Two-Dimensional Array
Both numeric and alphanumeric arrays can be manipulated with the Sort statements. Numeric and alphanumeric array elements are defined by the assigned array name, e.g., either A() or A$( )$, respectively. For example, in the following array the value in element (1,2) is A and the value in element (3,4) is B.

```
  | Z | A | Q | N |
  | V | W | X | Z |
  | Z | Z | Q | B |
  | R | S | T | U |
```

Figure 1-2. A Two-Dimensional Alphanumeric Array

The rules of the BASIC language require that every array be appropriately named and properly dimensioned with a DIM or COM statement prior to the variable's use in a program statement. This is required in order to reserve space for the array variables in memory. Space may be reserved for more than one array in a single dimension statement by separating the array names with commas. The space must be indicated explicitly; expressions are not allowed. The COM statement defines arrays which are to be used in common by several programs, a feature which is useful for program chaining. A COM statement must not change the dimensions of a previously defined common variable. If an array's dimensions are not specified in a DIM or COM statement the array will automatically be dimensioned as a 10 x 10 matrix. If the array is alphanumeric, each element in the array will have a length of 16 bytes. The following statement defines and dimensions the two-dimensional alphanumeric array illustrated in Figure 1-2.

```
10 DIM A$(4,4)
```

For alphanumeric arrays, the length of each element in the array can be specified by the programmer as any length between one byte and 64 bytes, inclusive. For example:

```
10 DIM A$ (4,4) 64
```

would specify a 16-element array with 64 bytes in each element (1024 bytes total).
The length of each element in the array, the total number of elements in the array, and the available memory size are the factors which limit the size of arrays which can be specified for use with the Sort statements. The system uses a single byte to represent each subscript of an array internally. Since the maximum binary number which can be represented in one byte (eight bits) is 255, each subscript of a two-dimensional array is restricted to a maximum value of 255. In other words, each row is limited to a maximum of 255 elements or each column is limited to a maximum of 255 rows. The maximum number of elements in any array is limited to 4096. The size of an array is also limited to the machine's total memory capacity.

NOTE:

Subscripts defined in DIM statements must be explicitly defined positive integers (1 to 255). Zero is not allowed as a defining subscript. Once defined, variables can be used as subscripts. In some Sort statements, a subset of an element can be defined. When memory space is initially allocated, (dimensioned) numeric array elements are set to zero, and alphanumeric array elements are set to spaces (HEX(20)).

1.4 INTERNAL STORAGE

All data is physically stored by the Wang System 2200 in a field of one or more contiguous bytes. The format in which data are stored internally depends upon whether the data are numeric values, alphanumeric values, or MAT CONVERTed numeric values. To identify each variable in memory, the system automatically inserts several bytes of control information at the beginning of the variable area. These additional bytes, however, are completely "transparent" to the programmer (i.e., they are used exclusively by the operating system and cannot be accessed by the application program). The number of control bytes required differs according to whether the array is alpha or numeric. Although control bytes represent a fixed overhead for each variable defined in a program, the amount of memory they require is insignificant.
Alphanumeric data are stored internally as a series of bytes. Each data element can range in length from one to sixty-four bytes, where each byte represents a single character.

A numeric value is stored internally in an eight-byte exponential form. The first half of the first byte contains a code for the relationship between the signs of the mantissa and the exponent. The next two half-bytes contain the exponent ($10^{-99} \leq E \leq 10^{99}$) in reverse order (low-order digit, then high-order digit). The remaining 6 1/2 bytes contain the 13 digits of the mantissa. One digit is in each half-byte (see Figure 1.3). The standard numeric format is not good for sorting, however, because it does not describe a number's relative magnitude when reading consecutively across the byte field as is done during comparisons (sorting) when using the Sort statements. The MAT CONVERT statement restructures numeric data into a form suitable for sorting.

![Diagram of the Eight Byte Internal Numeric Storage Field](image)

**Figure 1-3. The Eight Byte Internal Numeric Storage Field**

### INTERNAL NUMERIC STORAGE RELATIONSHIPS

<table>
<thead>
<tr>
<th>1st. half-byte</th>
<th>indicates</th>
<th>example</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>mantissa and exponent both positive</td>
<td>+1.0</td>
</tr>
<tr>
<td>8</td>
<td>mantissa positive, exponent negative</td>
<td>+0.1</td>
</tr>
<tr>
<td>9</td>
<td>mantissa and exponent both negative</td>
<td>-0.1</td>
</tr>
<tr>
<td>1</td>
<td>mantissa negative, exponent positive</td>
<td>-1.0</td>
</tr>
</tbody>
</table>

A MAT CONVERTed value is also stored in an exponential field (see Figure 1.3). However, the format of a MAT CONVERTed value is alphanumeric, not the standard internal numeric format. The MAT CONVERT format restructures numeric values so that the relationships between a number's sign, exponent, and mantissa, which describe its relative magnitude, occur consecutively in the first bytes of the field.
In the MAT CONVERTed format, the first half-byte represents the relationship between the signs of the mantissa and the exponent. The next two half-bytes represent the high-order and low-order digits of the exponent \((10^{-99} \leq E \leq 10^{99})\) in their normal order. The exponent is given in decimal form if the signs of the mantissa and exponent are the same, or nines complement form if the signs of the mantissa and exponent differ. The remaining bytes of the value contain up to thirteen (13) digits of mantissa. These digits appear in decimal form if the sign of the mantissa is positive or in the nines complement decimal form if the sign of the mantissa is negative.

### MAT CONVERTed STORAGE RELATIONSHIPS

<table>
<thead>
<tr>
<th>1st half-byte</th>
<th>indicates</th>
<th>example</th>
</tr>
</thead>
<tbody>
<tr>
<td>9</td>
<td>mantissa and exponent both positive</td>
<td>+1.0</td>
</tr>
<tr>
<td>8</td>
<td>mantissa positive, exponent negative</td>
<td>+0.1</td>
</tr>
<tr>
<td>1</td>
<td>mantissa and exponent both negative</td>
<td>-0.1</td>
</tr>
<tr>
<td>0</td>
<td>mantissa negative, exponent positive</td>
<td>-1.0</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>2nd and 3rd half-bytes</th>
<th>indicates</th>
<th>example</th>
</tr>
</thead>
<tbody>
<tr>
<td>decimal</td>
<td>mantissa and exponent both positive</td>
<td>+1.0</td>
</tr>
<tr>
<td>complemented</td>
<td>mantissa positive, exponent negative</td>
<td>+0.1</td>
</tr>
<tr>
<td>decimal</td>
<td>mantissa and exponent both negative</td>
<td>-0.1</td>
</tr>
<tr>
<td>complemented</td>
<td>mantissa negative, exponent positive</td>
<td>-1.0</td>
</tr>
</tbody>
</table>

Using the five values of this number line example \((A(1) = -1.0, A(2) = -0.1, A(3) = 0, A(4) = +0.1, A(5) = +1.0)\), Figure 1-4 compares the difference between the values when stored in the internal numeric storage format and MAT CONVERTed sort format.

<table>
<thead>
<tr>
<th>-1.0</th>
<th>-0.1</th>
<th>0</th>
<th>+0.1</th>
<th>+1.0</th>
</tr>
</thead>
<tbody>
<tr>
<td>mantissa (-)</td>
<td>mantissa (-)</td>
<td>mantissa (+)</td>
<td>mantissa (+)</td>
<td></td>
</tr>
<tr>
<td>exponent (+)</td>
<td>exponent (-)</td>
<td>exponent (-)</td>
<td>exponent (+)</td>
<td></td>
</tr>
</tbody>
</table>

### INTERNAL NUMERIC FORMAT

| A(1) | 100100000000000000000000 |
| A(2) | 910100000000000000000000 |
| A(3) | 000000000000000000000000 |
| A(4) | 810100000000000000000000 |
| A(5) | 000100000000000000000000 |

### MAT CONVERTed FORMAT

| A$$(1) | 09989999999999999 |
| A$$(2) | 10189999999999999 |
| A$$(3) | 80000000000000000 |
| A$$(4) | 89810000000000000 |
| A$$(5) | 90010000000000000 |

Figure 1-4. Comparison of Internal Storage Formats
Notice how values are stored sequentially ascending in sort format, with each data element contained in a separate element of the alphanumeric array. Each element normally contains eight bytes. If the elements of the alpha array are specified to contain more than eight bytes, the stored value is padded with spaces (at the right). If the elements of the alpha-array are specified to contain less than eight bytes, the value is truncated; least significant digits are lost. The truncation feature can conserve memory when it is known that all values to be MAT CONVERTed will have fewer than 13 significant digits.

1.5 SORT/MERGE OPERATIONS

An internal sort is one in which all sorting occurs inside the memory of the computer. An external sort is performed when the memory is insufficient to contain the entire file to be sorted and various peripheral devices must be used for storage of permanent and intermediate data files. The most common sort or sort/merge techniques are performed externally.

Of the many sorting techniques which order data, a common technique which utilizes the MAT CONVERT, MAT COPY, MAT MOVE, MAT SORT and MAT MERGE statements is described below. This example contains a Convert Phase, Sort Phase, Merge Phase, and Move Phase, in that order.

The Sort key is the basis for ordering the data records. The Sort key can contain any number of variables or fields from the data record or even the entire record. MAT COPY is often used to concatenate data records and/or portions of data records to create the Sort key. Using a short Sort key improves running time because comparisons between the keys for sorting occur many times during a sort. In building the Sort key, note that both numeric and alphanumeric data must be compared in the same operation, character-by-character. Therefore, all data must be in sort format.

The Convert Phase

Numeric values are stored in a floating point exponential format which is optimum for numerical calculations. These numeric values must be converted for sorting purposes to an appropriate alphanumeric equivalent using MAT CONVERT. If the full thirteen digits of the mantissa are not required, MAT CONVERT can truncate the mantissa to conserve memory and shorten the Sort key.

The Sort Phase

In this phase, MAT SORT is used to sort the initial data into several ordered strings (small sorted groups) by setting up a subscript array (locator-array) whose elements point in sorted order to the locations of the records which are in memory. The data records to be sorted are ordered on the basis of a Sort key. The data records are read in groups, Sort keys are built for each group, and the records and/or keys are sorted into strings and stored on disk or tape in at least two Merge files.
Although the size of a string is not restricted by memory capacity, the number of records and/or keys initially put into each string is usually determined by the amount of memory available.

The Merge Phase

The Merge phase generally consists of a number of merge passes. In each merge pass, strings from two or more Merge files from the Sort phase are read, combined into longer strings, and stored in an output file. The process is repeated until a single string containing the entire file in sorted order is created. A given string need not be completely stored in memory at one time during the merge process; it can be loaded into memory in segments.

MAT MERGE creates the locator-array used to merge the input string segments. Each row of the merge-array represents one string segment from the input Merge file. The strings contain the records or keys on which comparisons are made. When MAT MERGE first executes, the first key in each row is compared with the first key in every other row, and the lowest key is selected. The subscript of the lowest key is placed in the locator-array and this key is eliminated from future comparisons. MAT MERGE is then executed again. The lowest key not yet merged is again sought. MAT MERGE execution terminates when a segment from the Merge file (a row) is exhausted or the locator-array is full.

The Move Phase

The Move phase consists of moving data from the merge-array to an output-array in the order specified by the locator-array. MAT MOVE transfers the merging records into an array where segments of the output file are being collected. Once a merge-array input segment has been exhausted, the row can be refilled using MAT COPY. This process is repeated until all strings from the Merge files have been exhausted and a single sorted string containing all records from the original input file has been created.
1.6 DESCENDING SORTS

Sometimes it is necessary to perform a sort in descending order. This can be accomplished by inverting the order of an ascending sort or by complementing (using XOR or BOOL6) the characters in the Sort key. For numeric data, complementing must be done after data have been converted to sort format using MAT CONVERT.

Consider the characters "A" (whose decimal and binary equivalents are 65 and 0100 0001 respectively) and "Z" (whose decimal and binary equivalents are 90 and 0101 1010 respectively). XOR performs the exclusive OR logical binary operation which outputs a 1-bit when the corresponding bits in the two arguments are different. For example:

\[
\begin{align*}
A &= 0100 0001 \\
FF &= 1111 1111 \\
\text{XOR} &= 1011 1110
\end{align*}
\]

\[
\begin{align*}
Z &= 0101 1010 \\
FF &= 1111 1111 \\
\text{XOR} &= 1010 0101
\end{align*}
\]

The complement of the code for "A" (whose decimal and binary equivalents are now 190 and 1011 1110 respectively) will sort after the complement of the code for "Z" (whose decimal and binary equivalents are now 165 and 1010 0101 respectively).

Example 1:

A$( ) is a Sort key to be complemented.

\[
100 \text{ XOR (A$( ),FF)}
\]

places all Sort keys in reverse sequence.

Example 2:

B$(1) is an array element representing a Sort key and record. The sixth through tenth characters of this element are part of the Sort key to be complemented for a descending sort.

\[
200 \text{ XOR (STR(B$(1),6,5),FF)}
\]

complements the sixth through tenth characters of this Sort key.
Block diagrams for a typical program using Sort statements are shown in Figure 1-5 and Figure 1-6.

- Read a group of records from disk to form a string.
- Build Sort keys for each record.
  - Use MAT CONVERT to reformat numeric values in Sort keys; use MAT COPY to group records/keys.
- Sort records/keys to order string.
  - Use MAT SORT to prepare locator-array for sorted output.
- Group and store records/keys as strings on a Merge file on disk.
  - Use MAT MOVE to place records/keys in sorted order according to pointers of locator-array.

- All records done?
  - no
  - yes

Go to MERGE PHASE (Figure 1-6).

NOTE:

Due to the many simultaneous operations that proceed when MAT MERGE executes, there are no simple examples to illustrate this statement.

Figure 1-5. Block Diagram of a Typical Sort Program (Sort Phase)
Figure 1-6. Block Diagram of a Typical Sort Program (Merge Phase)
Example 3: An External Sort

In this example there are three sorted data files on disk (INPUT1, INPUT2 and INPUT3). Each data file has logical records which contain 50 elements; each element contains 8 bytes. The program merges the three files into a single file called output. The diagram illustrates the flow of data from the input files through the merge process, to the output buffer, and then to the output file.

The merging scheme proceeds as follows:

1. Data is brought into memory from the disk files utilizing an input buffer to transfer whole records at once.

2. A merge-array is created, M$$(), using MAT COPY. In this example, MAT COPY is in a subroutine.

3. The first N elements of the primary work-array, W1$$(), are initialized to 1.

4. MAT MERGE is called to create the subscript locator-array.

5. MAT MOVE uses the locator-array to transfer data from the merge array to the output buffer. The movement of data ceases when the locator-array has been emptied or when an element filled with zeroes is reached. MAT MOVE automatically keeps track of the number of elements actually moved.

6. When the output buffer is filled, all data stored in it is written to the output file. The buffer is then ready to receive more data from another execution of MAT MOVE.

7. The last element in the primary work-array is checked (with the VAL function) to see if a row in the merge-array has been completely scanned. If all elements in a merge-array row have been used, the row is refilled with data from the input file and the appropriate element in the primary-work-array is reset to 1.

8. Steps 4 through 8 are repeated until the first element in the locator-array is filled with zeroes when examined by the MAT MOVE statement.
Figure 1-7. Schematic Diagram of MAT MERGE External Sort
Program Listing

10 REM ARRAY DEFINITIONS.................................
20 DIM M$(3,50)8: REM MERGE ARRAY
30 DIM I$(50)8: REM INPUT BUFFER
40 DIM O$(50)8: REM OUTPUT BUFFER
50 DIM W1$(4): REM WORK BUFFER 1
60 DIM W2$(3): REM WORK BUFFER 2
70 DIM S$(50): REM SUBSCRIPT BUFFER
80 REM OPEN THE DATA FILES ON DISK........................
90 SELECT #1 310, #2 310, #3 310, #4 310
100 DATA LOAD DC OPEN F #1, "INPUT1"
110 DATA LOAD DC OPEN F #2, "INPUT2"
120 DATA LOAD DC OPEN F #3, "INPUT3"
130 DATA LOAD DC OPEN F #4, "OUTPUT"
140 REM FILL THE MERGE ARRAY..............................
150 FOR I = 1 TO 3
160 GOSUB '40(I)
170 NEXT I
180 REM INITIALIZE WORK BUFFER 1...........................
190 INIT(01) W1$(())
200 M=1
210 REM MERGE................................................
220 MAT MERGE M$(()) TO W1$(()), W2$(()), S$(())
230 IF S$(1)=HEX(0000) THEN 480: REM EXIT IF DONE
240 REM MOVE THE MERGED DATA TO THE OUTPUT BUFFER......
250 S=1
260 N=50
270 MAT MOVE M$(()), S$(S), N TO O$(M)
280 M=M+N: REM M = NO. OF ELEMENTS IN OUTPUT BUFFER
290 REM PUT DATA INTO OUTPUT FILE IF OUTPUT BUFFER FULL.
300 IF M<50 THEN 350
310 DATA SAVE DC #4, O$(())
320 M=1
330 S=S+N
340 IF S<51 THEN 260: REM BRANCH IF MORE DATA TO MOVE
350 REM CHECK MERGE TERMINATION FLAG......................
360 T=VAL(W1$(4))
370 IF T=0 THEN 220: REM BRANCH IF NO ROWS OF M$(()) EMPTY
380 GOSUB '40(T): REM REFILL EMPTY ROW OF M$(())
390 GOTO 220
400 REM......................................................
410 DEFN'40(R): REM READ THE NEXT BLOCK FROM SPECIFIED
420 REM INPUT FILE AND PUT INTO MERGE ARRAY
430 DATA LOAD DC #R, I$(())
440 IF END THEN 470
450 MAT COPY I$(()) TO M$(())<R-1>*400+1,400>
460 W1$(R)=HEX(01): REM RESET APPROPRIATE WORK BUFFER ELEMENT
470 RETURN
480 END
Example 4: An Internal Sort

In this example, two arrays, A$() and B$(), are internally merged. Their data are given in a DATA statement. Only a listing of this routine is provided, followed by a printout of the data which are displayed on the CRT. The routine uses MAT COPY to fill the input array, A$(); INIT to initialize the work vector, W1$(), and the locator-array, L$(); and MAT MERGE to fill the locator-array. Once L$() has been filled, the data are sent to an output array, O$(), with MAT MOVE. When the first element of the locator-array is still zero after an execution of MAT MERGE, the merge operation is considered complete and the final merged array is displayed. Not all arrays can be displayed directly with a PRINT statement. The HEXP Keat statement must be used for those arrays which cannot be displayed directly by a PRINT statement.

Program Listing

10 REM THIS ROUTINE ILLUSTRATES USE OF MAT COPY, MAT MERGE
20 REM AND MAT MOVE
30 REM DEFINE THE ARRAYS
40 DIM A$ (4) 5, I$ (4) 5, B$ (4) 5
50 DIM M$ (2, 4) 5, O$ (4) 5, W1$ (3) 1, W2$ (2) 2
60 DIM L$ (4) 2, J$ (9) 5, K$ (16) 5
70 S=1; R=1
80 REM GET THE DATA TO BE MERGED
90 FOR I=1 TO 4:READ A$ (I) :NEXT I:FOR I=1 TO 4:PRINT A$ (I) , :NEXT I
100 FOR I=1 TO 4:READ B$ (I) :NEXT I:FOR I=1 TO 4:PRINT B$ (I) , :NEXT I
110 STOP "ALL DATA HAVE BEEN INPUT"
120 PRINT HEX (03)
130 PRINT "THIS IS THE ARRAY I$#1"
140 REM FILL THE MERGE ARRAY M$ USING MAT COPY
150 FOR I=1 TO 4:I$ (I) =A$ (I) :PRINT I$ (I) , :NEXT I:MAT COPY I$ () TO M$ () <1,20> :STOP
160 FOR I=1 TO 4:I$ (I) =B$ (I) :PRINT I$ (I) , :NEXT I:PRINT ""
170 MAT COPY I$ () TO M$ () <21,20>
180 PRINT "THIS IS THE ARRAY I$#2":STOP
190 PRINT "HEX OF THE MERGE ARRAY M$, OUTPUT OF MAT COPY"
200 FOR I=1 TO 2:FOR J=1 TO 4:HEXPRI NT M$ (I, J) :NEXT J:NEXT I:STOP
210 REM INITIALIZE THE WORK VECTOR W1$ TO 1
220 INIT (01), W1$ ( )
230 PRINT HEX (03)
240 PRINT "THE MERGE ARRAY HAS BEEN FILLED AND THE WORK VECTOR INITIALIZED AS:"
250 PRINT "W1$ =":FOR I=1 TO 3:HEXPRI NT W1$ (I) :NEXT I:STOP
260 REM CREATE THE LOCATOR ARRAY L$ WITH MAT MERGE
270 M=1
280 INIT (00), L$( )
290 MAT MERGE M$ () TO W1$ ( ) , W2$ ( ) , L$ ( ) :REM ********************
300 PRINT "MAT MERGE HAS BEEN EXECUTED":STOP
310 IF L$ (1) =HEX (0000) THEN S70:REM EXIT WHEN DONE
320 S=1
330 REM DISPLAY THE CONTENTS OF L$ AND W1$
340 PRINT HEX (03):PRINT "THE LOCATOR ARRAY L$ =":FOR I=1 TO 4:HEXPRI NT L$ (I) :NEXT I:STOP
350 PRINT HEX (03):PRINT "WORK VECTOR FROM MAT MERGE IS NOW" FOR I=1 TO 3

15
Program Listing (Continued)

HEXPRINT W1$ (I):NEXT I:STOP
360 REM MOVE THE MERGE ARRAY TO THE OUTPUT BUFFER O$ WITH MAT MOVE
370 PRINT HEX (03): PRINT "COUNTERS AND THE OUTPUT BUFFER ARE:"
380 N=4:PRINT "M=" , M," S=" , S," N=" , N
390 MAT MOVE M$ () , L$ (S) , N TO O$ (M)
400 PRINT "N=" , N," ELTS WERE MOVED"
410 REM PUT DATA INTO OUTPUT ARRAY IF OUTPUT BUFFER FULL
420 M=M+N:REM NO. OF ELTS. (ELEMENTS) PLACED IN OUTPUT BUFFER
430 R=R+1:IF M=4 THEN 520
440 M=1:P=1:Q=4
450 FOR I=P TO Q: J$ (I) =O$ (I):NEXT I
460 MAT COPY O$ () TO K$ () <(R-1)*20+1,20>
480 IF S<5 THEN 380:REM RETURN TO MOVE IF MORE DATA TO MOVE
490 REM DISPLAY THE CONTENTS OF O$
500 PRINT "OUTPUT ARRAY BUFFER"
510 FOR I=1 TO 4:PRINT J$ (I) , :HEXPRINT 0$ (I) , :NEXT I:STOP
520 REM CHECK TERMINATION OF MERGE
530 T=VAL (W1$ (3)) :PRINT "T=" , T:STOP :IF T=0 THEN 280
540 IF L$ (1) <> HEX (0000) THEN 280
550 PRINT HEX (03)
560 REM DISPLAY THE MERGED ARRAY
570 PRINT "FINAL MERGED ARRAY"
580 FOR I=1 TO 4:J$ (I) =O$ (I):NEXT I
590 FOR I=1 TO 8:PRINT K$ (I) :NEXT I
600 FOR I=1 TO 4:PRINT J$ (I) , :HEXPRINT 0$ (I) , :NEXT I:STOP
610 PRINT "":PRINT "L$=":FOR I=1 TO 4:HEXPRINT L$ (I) :NEXT I:STOP
620 PRINT "":PRINT "W1$=":FOR I=1 TO 3:HEXPRINT W1$ (I) :NEXT I
630 DATA "JAKE","JOHN","KARL","KATHY","JANE","JILL","KING","Kitty"
640 END

Program Printout

JAKE     JOHN     KARL     KATHY
JANE     JILL     KING     KITTY
THIS IS THE ARRAY I$#1
JAKE     JOHN     KARL     KATHY
JANE     JILL     KING     KITTY
THIS IS THE ARRAY I$#2
HEX OF THE MERGE ARRAY M$, OUTPUT OF MAT COPY
4A14B4520
4A4F484E20
4B41524020
4B41544859
4A414E520
4A494C420
4B494E4720
4B49544549
THE MERGE ARRAY HAS BEEN FILLED AND THE WORK VECTOR INITIALIZED
AS:
W1$=
 01
 01
 01
MAT MERGE HAS BEEN EXECUTED
THE LOCATOR ARRAY L$=
 0101
 0201
 0202
 0102
WORK VECTOR FROM MAT MERGE IS NOW:
 03
 03
 00
COUNTERS AND THE OUTPUT BUFFER ARE:
M=  1    S=    1
N=  4
N=  4    ELTS. WERE MOVED
P=  5    Q=    8
S=  5
OUTPUT ARRAY BUFFER
JAKE  4A44B4520
JANE  4A44E4520
JILL  4A494C4C20
JOHN  4A4F484E20
T=    0
MAT MERGE HAS BEEN EXECUTED
THE LOCATOR ARRAY L$=
 0103
 0104
 0000
 0000
WORK VECTOR FROM MAT MERGE IS NOW:
FF
 03
 01
COUNTERS AND THE OUTPUT BUFFER ARE:
M=  1    S=    1
N=  4
N=  2    ELTS. WERE MOVED
T=    1
MAT MERGE HAS BEEN EXECUTED
THE LOCATOR ARRAY L$=
 0203
 0204
 0000
 0000
WORK VECTOR FROM MAT MERGE IS NOW:
Program Printout (Continued)

FF
FF
02
COUNTERS AND THE OUTPUT BUFFER ARE:
M= 3 S= 1
N= 4
N= 2  ELTS. WERE MOVED
P= 3 Q= 6
S= 3
M= 1 S= 3
N= 4
N= 0  ELTS. WERE MOVED
T= 2
MAT MERGE HAS BEEN EXECUTED
FINAL MERGED ARRAY

JAKE
JANE
JILL
JOHN
KARL  4B41524C20
KATHY  4B41544859
KING   4B494E4720
KITTY  4B49545459

L$=
0000
0000
0000
0000
0000

W1$=
FF
FF
02
CHAPTER 2  SORT STATEMENTS

Chapter 2 contains a discussion of syntax and examples using the Sort statements. As with the other verbs and statements of the BASIC language, syntax is critically important when using the Sort statements. In addition, several of the Sort statements have array dimensioning requirements which must be followed. If the rules and restrictions presented in this manual are not followed exactly, programs using the Sort statements will not work.

In the general form provided for each MAT statement, arguments in brackets [ ] are optional. Stacked items in braces { } are alternatives; one must occur. Uppercase words and punctuation (commas, parentheses, etc.) represent actual characters in the statement which must occur exactly as shown. Lowercase words represent parameters which the programmer can specify.

No array to be used with the Sort statements can contain more than 4096 elements. The locator-array must always have elements of length=2.

NOTE:

Any data set containing numeric values must be changed to Sort format (alphanumeric) with MAT CONVERT before being used with the MAT SORT or MAT MERGE statement.

Do not use MAT REDIM on an array to reduce its total number of bytes and then execute a Sort statement operation on the array. MAT REDIM may be used with an array subsequently operated on by a Sort statement only if the total number of bytes in all elements after the MAT REDIM equals the total number before the MAT REDIM.
MAT CONVERT

General Form:

MAT CONVERT numeric-array TO alpha-array [(s,n)]

Where:  (s,n) are expressions designating a field within each element of the
         alpha-array used to store the converted value.  If (s,n) are
         omitted, the entire array is used.

         s specifies the starting position of the field (0 < s <= bytes in the
         array).

         n specifies the number of bytes in the field (0 < n <= bytes in the
         array - s+1).

         The alpha-array must have at least as many elements as the
         numeric-array.

Purpose:

MAT CONVERT converts numeric-array-elements to alpha-array-elements
which can be ordered in proper numeric sequence with MAT SORT. The format of
data passed through the MAT CONVERT statement is called sort format.

Values in sort format can be stored in a specified field of each
alpha-array element by using the field limiting expressions (s,n). The number
of bytes specified in each field must be at least two. If more than eight
bytes are specified, the value is truncated at the right, two digits per
byte. For example, the statement:

    MAT CONVERT N() TO A$() (3,5)

specifies that the numeric values from the array N() are to be stored in the
third through seventh bytes of each element of alpha-array A$(). If less than
eight bytes are specified, the field is padded with zeroes.

Examples of valid syntax:

    MAT CONVERT A() TO A$() (6,8)
    MAT CONVERT N() TO A$()
Example 5: A Program Using MAT CONVERT

In the routine below, the numeric-array N() contains four numeric elements which are passed to A$( ) and B$( ) with MAT CONVERT statements and printed with the appropriate HEXPRINT statements. The field expressions in line 90 specify that each converted element value from N() is to be placed in the corresponding element of B$( ) , starting with the second character of each element of B$( ) .

10 DIM N (4) ,A$(2, 2) 3, B$(4) 8
20 N (1) = 123: N (2) = -456: N (3) = .123: N (4) = 0
30 PRINT "NUMERIC ARRAY, N :"  
40 FOR I = 1 TO 4: PRINT , N (I) : NEXT I
50 MAT CONVERT N() TO A$( )
60 PRINT "ALPHA ARRAY, A$( ) :"  
70 PRINT , : HEXPRINT A$(1, 1) : PRINT , : HEXPRINT A$(1, 2)
80 PRINT , : HEXPRINT A$(2, 1) : PRINT , : HEXPRINT A$(2, 2)
90 MAT CONVERT N() TO B$(2, 3)
100 PRINT "ALPHA ARRAY, B$( ) :"
110 FOR I = 1 TO 4: PRINT , : HEXPRINT B$(I) : NEXT I

The converted values are stored in both A$( ) and B$( ) with an exponent and three digits of the mantissa. In the printed output, hex(20) represents the space character.

Output from Program Using MAT CONVERT

NUMERIC ARRAY, N( ):

<p>| | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>123</td>
<td></td>
<td></td>
</tr>
<tr>
<td>-456</td>
<td></td>
<td></td>
</tr>
<tr>
<td>.123</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

ALPHA ARRAY, A$( ):

<p>| | | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>902123</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>097543</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>898123</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>800000</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

ALPHA ARRAY, B$( ):

<p>| | | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>2090212320202020</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2090754320202020</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2089812320202020</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2080000020202020</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

FIELD(2, 3) = elements 2, 3 and 4 only

If it is necessary to reconvert values which have been passed through a MAT CONVERT statement back into standard internal numeric format, the Wang "Unconvert" utility should be used. A listing of this utility appears below.
Program Listing of the "Unconvert" Routine

1000 REM CONVERT BACK FROM SORT FORMAT TO NUMERIC
1010 REM ENTRY Z$ = NUMBER IN SORT FORMAT
1020 REM Z1 = LENGTH OF ALPHA VARIABLE
1030 REM RETURN Z = NUMBER
1040 DIM Z$8,Z1$1,Z2$2,Z3$1
1050 DEFFN'200 (Z$,Z1)
1060 Z1$,Z2$ = Z$
1070 IF Z2$ = HEX (8000) THEN 1420 : REM ZERO EXIT
1080 Z$ = STR (Z$,2) :REM MOVE UP INTO PACKED FORMAT
1090 AND (STR (Z$,1,1), OF) :REM REMOVE EXTRA BITS
1100 REM EXTRACT THE EXPONENT
1110 Z3$ = STR (Z2$,2)
1120 AND (Z3$,F0) :REM SECOND EXP. DIGIT
1130 AND (Z2$,OF) :REM FIRST EXP. DIGIT
1140 OR (Z3$,Z2$) :REM EXP. REVERSED
1150 ROTATE (Z3$,4) :REM EXPONENT
1160 REM NOW DETERMINE THE SIGN
1170 AND (Z1$,F0) :REM SIGN BITS
1180 IF Z1$ = HEX (90) THEN 1350 : REM EXP. +; MANTISSA +
1190 IF Z1$ = HEX (10) THEN 1280 : REM EXP. -; MANTISSA -
1200 REM COMPLEMENT THE EXPONENT
1210 ADD (Z3$,66)
1220 XOR (Z3$,FF)
1230 IF Z1$ = HEX (80) THEN 1340 : REM EXP. -; MANTISSA +
1240 REM Z1$ = HEX (00) EXP. +; MANTISSA -
1250 Z1$ = HEX (10)
1260 GOTO 1300 : REM COMPLEMENT MANTISSA
1270 REM Z1$ = HEX (10)
1280 Z1$ = HEX (90)
1290 REM COMPLEMENT MANTISSA
1300 ADD (Z$,66)
1310 XOR (Z$,FF)
1320 AND (STR(Z$,1,1),OF)
1330 REM INSERT SIGN
1340 OR (Z$,Z1$)
1350 STR (Z$,8) = Z3$ : REM INSERT EXPONENT
1360 REM ZERO UNUSED BYTES
1370 IF Z1>7 THEN 1390
1380 INIT (00) STR (Z$,Z1,8-Z1) : REM ZERO UNUSED BYTES
1390 UNPACK (+#.############)Z$ TO Z
1400 RETURN
1410 REM ZERO EXIT
1420 Z = 0
1430 RETURN
General Form:

MAT COPY [-] source-alpha-array [\langle s,n \rangle] TO [-] output-alpha-array [\langle s,n \rangle]

Where:  
(s,n) are expressions designating a field within either array. If 
(s,n) are omitted, the entire array is used.

s specifies the starting position of the field \(0 < s \leq \) bytes in the array.

n specifies the number of bytes in the field \(0 < n \leq \) bytes in the array - s + 1.

Each array is treated as a contiguous string of bytes, ignoring 
element boundaries.

Purpose:

MAT COPY transfers data byte-by-byte from the source-alpha-array to the 
output-alpha-array. An array is treated as one contiguous character string, 
i.e., element boundaries are ignored. MAT COPY can be used to construct new 
arrays from old ones, combine or divide array elements, move data within 
arrays, and using the inverse parameter (-), store data in reverse order 
within arrays.

A portion of an array can be specified by using the field limiting 
expressions (s,n). "s" is the position of the first byte to be used in the 
array. The position is found by counting bytes across the first row from 
left-to-right, then across the second row, etc., until the desired byte is 
encountered. "n" specifies the number of bytes to be used. Data are moved 
until the output-array is filled. If the amount of data to be moved is 
insufficient to fill the specified portion of the output-array, the remainder 
of the array is filled with spaces.

If a minus sign (-) precedes the input-array name (or its specified 
portion), data are taken from this array in reverse order and stored left 
justified. The first byte moved is the last byte specified, and so on. If a 
minus sign (-) precedes the output-array, data are stored in the output-array 
in reverse order right justified, i.e., the first byte is stored in the last 
byte specified, etc.

Examples of valid syntax:

MAT COPY B$(\cdot) TO C$(\cdot)
MAT COPY - A$(\cdot) TO B$(\cdot) <3,27>
MAT COPY A$(\cdot) < X*Y, 100/X > TO -Q$(\cdot) <10,20>
Example 6: MAT COPY

In this example, A$(i) has been dimensioned as a five-element array in which each element contains two bytes. B$(i) is dimensioned as a seven-element array in which each element contains two bytes. A$(i) contains the characters A to K, and these data are copied to B$(i). As statement 30 is changed, the result is changed as shown below.

10 DIM A$(5)2, B$(7)2
20 FOR I = 1 TO 5: READ A$(I): NEXT I
30 MAT COPY A$(i) TO B$(i)
40 DATA "AB", "CD", "EF", "GH", "JK"
50 FOR I = 1 TO 5: PRINT STR (A$(I), 1);: NEXT I
60 PRINT
70 FOR I = 1 TO 5: PRINT STR (B$(I), 1);: NEXT I
80 PRINT

Output from MAT COPY Example

A$(i) =

| A | B | C | D | E | F | G | H | J | K |

30 MAT COPY A$(i) TO B$(i)

B$(i) =

| A | B | C | D | E | F | G | H | J | K | space | space |

30 MAT COPY A$(i) TO - B$(i)

B$(i) =

| space | space | K | J | H | G | F | E | D | C | B | A |

30 MAT COPY - A$(i) TO B$(i)

B$(i) =

| K | J | H | G | F | E | D | C | B | A | space | space |

30 MAT COPY - A$(i) TO - B$(i)

B$(i) =

| space | space | A | B | C | D | E | F | G | H | J | K |
MAT MERGE

General Form:

MAT MERGE merge-alpha-array TO work-vector-1, work-vector-2, locator-array

Where: The merge-array must be a two-dimensional alpha-array with a maximum of 254 rows or columns; the number of rows (n) must be >1. The elements in the merge-array must already be sorted.

Work-vector-1 must be one-dimensional and possess at least one more element than the merge-array has rows. Each element must have length = 1 and be initialized to HEX(01) before initial use of the MAT MERGE statement.

Work-vector-2 must be one-dimensional and possess at least as many elements as the merge-array has rows. Each element must have length = 2. Although work-vector-2 is not used by the user's program, it must be defined for system use.

The locator-array must be one-dimensional and should possess at least as many elements as a single row of the merge-array. (It should have as many elements as possible because the larger the locator-array, the faster the merge.) Each element of the locator-array must have length = 2.

Each row of the merge-array must be presorted.

Purpose:

MAT MERGE enables the programmer to quickly combine the elements of several sorted data files into a single file by creating a locator-array of their subscripts in ascending order.

Each row of the merge-array represents a set of sorted data elements (one datum per element) to be merged and essentially constitutes a "merge buffer" for a given input file. The merge operation occurs in a series of passes where in each pass, the program fills the locator-array with elements from the merge-array, empties the locator-array to the output buffer, refills any emptied rows of the merge-array, and resets the pointers in work-vector-1. As each pass occurs, the data in each of the rows of the merge-array are scanned and compared. The subscripts corresponding to these data are then stored in the locator-array in order of increasing data value. The location pointer of work-array-1 is then updated to the next element in each row which is to be merged into the locator-array. When the locator-array is filled, the contents are written at the output device. MAT COPY replenishes empty rows in the merge-array. MAT MOVE moves the merged data from the locator-array to an output-array. These processes must be repeated until all elements in the merge-array have been exhausted. The merge operation halts when one of the following conditions occur.

1. The locator-array is filled with subscripts.

2. A row of the merge-array has been completely used (emptied of elements).
In the last element in work-vector-1, a condition code is returned which specifies why the merge pass terminated. The code is as follows:

00 - locator-array full
01 to FF - row number of emptied merge-array row

Each element of work-vector-1 receives the subscript of the next element in the row which will be compared with the elements in the other rows. All elements of work-vector-1 must be initialized to hex(01) (using INIT) before initial execution of MAT MERGE. Once a merge-array element is selected, its subscript is placed in the locator-array, and the work-vector-1 pointer increments to the next value in the row to be compared. When a row has been completely scanned, hex(FF) is placed as the pointer for that row in work-vector-1. The last element of work-vector-1 receives a condition code during MAT MERGE which indicates why the merge pass was halted. (If a row in the merge-array was exhausted of elements, the code is 01 to FF, designating the row number of the emptied row. If the locator-array was filled, the code is 00). The user's program must then refill that row of the merge-array with data, reinitialize the respective subscripts for that row of the merge-array in work-vector-1 to hex(01) and move the contents of the locator-array to the output buffer. If there are insufficient data to fill the row, the data must be right-justified in the row, and the starting subscript in the work-vector set appropriately. If no data remain to be placed in an empty row of the merge-array, hex(FF) is left in the corresponding element of work-vector-1 indicating that MAT MERGE is to ignore that row during successive merge passes. When MAT MERGE determines that all rows are to be ignored (hex(FF) is the pointer in all rows), hex(0000) is returned to the next element of the locator-array. The contents of the locator-array are again moved to the output buffer and execution of the merge phase is complete.

Examples of valid syntax:

10 DIM A$(10,50)10,W1$(11)1, W2$(10)2, S$(50)2
20 MAT MERGE A$() TO W1$(), W2$(), S$()

Example 7. A Three-Row Merge

In the following example, three rows of a merge-array A$ are merged using MAT MERGE. Each row may be regarded as a merge buffer. Prior to the merge, the data in each row must be sorted as in the following example where each row in the array is already in alphabetical order.

<table>
<thead>
<tr>
<th>col: 1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>6</th>
</tr>
</thead>
<tbody>
<tr>
<td>row</td>
<td>A</td>
<td>D</td>
<td>H</td>
<td>I</td>
<td>L</td>
</tr>
<tr>
<td>A$()=</td>
<td>B</td>
<td>C</td>
<td>F</td>
<td>J</td>
<td>M</td>
</tr>
<tr>
<td></td>
<td>E</td>
<td>G</td>
<td>K</td>
<td>N</td>
<td>O</td>
</tr>
</tbody>
</table>

merge buffer 1

merge buffer 2

merge buffer 3
Work-vector-1 contains the pointers to the starting or current element in each row to be scanned for the merge pass. Each element of work-vector-1 is initially set (using INIT) to hex(01). The first three elements of work vector-1 each correspond to a row of the merge-array, as follows:

\[
\begin{array}{cccc}
01 & 01 & 01 & 00 \\
\text{row 1} & \text{row 2} & \text{row 3} & \text{condition code} \\
\text{pointer} & \text{pointer} & \text{pointer} & \text{pointer}
\end{array}
\]

Given the arrays A$(\cdot)$ and W1$(\cdot)$ as described above, the following statements will produce the merge results described in the following example.

10 DIM A$(3,6)$, W1$(4)$, W2$(3)$, L$(12)$

20 MAT MERGE A$(\cdot)$ TO W1$(\cdot)$, W2$(\cdot)$, L$(\cdot)$

The subscript locator-array L$(\cdot)$ is filled with the subscripts of the twelve lowest-order elements from the three merge-array rows. If the locator-array has not been filled by the execution of MAT MERGE (this occurs when a merge-array row is exhausted before the locator-array is full), the element following the last valid subscript contains hex(0000). During the first merge pass, twelve subscripts are placed in the locator-array from the merge-array as follows:

\[
\begin{array}{cccccccccccc}
0101 & 0201 & 0202 & 0102 & 0301 & 0203 & 0301 & 0103 & 0104 & 0204 & 0303 & 0105 \\
\text{row 1} & \text{row 2} & \text{row 2} & \text{row 1} & \text{row 3} & \text{col 1} & \text{col 1} & \text{col 2} & \text{col 2} & \text{col 1} \\
\text{elements (A) (B) (C) (D) (E) etc. of A$(\cdot)$}
\end{array}
\]

Elements from all three rows in the merge-array are compared. MAT MERGE continues to extract subscripts and place them in ascending order in the locator-array until all the elements in a row have been exhausted or, as in this case, the locator-array is filled. The data which is in the locator-array must then be moved to an output-array using MAT MOVE.

The first merge pass terminates. Work-vector-1 is updated to indicate which element in each row is to be taken in the next merge pass. The first merge pass halted because the locator-array was full; thus the last element of W1$(\cdot)$ is set to hex zero (00). W1$(\cdot)$ now contains:

\[
\begin{array}{cccc}
06 & 05 & 04 & 00 \\
\text{row 1} & \text{row 2} & \text{row 3} & \text{condition code} \\
\text{elt 6} & \text{elt 5} & \text{elt 4} & \text{indicates locator-array full.} \\
(\text{elt} = \text{element in above row})
\end{array}
\]
The second merge pass now occurs. Four elements are placed in the locator-array, L$(\cdot)$, before this merge pass terminates. L$(\cdot)$ now contains:

\[
L$(\cdot)$ = \begin{array}{cccc}
0205 & 0304 & 0305 & 0106 & 0000 \\
(M) & (N) & (O) & (P)
\end{array}
\]

The second merge pass halted because row 1 of the merge-array was exhausted. W1$\$(\cdot)$ will thus contain:

\[
W1$\$(\cdot)$ = \begin{array}{cccc}
FF & 06 & 06 & 01
\end{array}
\]

If there is more data to be merged, row 1 of the merge-array must be refilled for re-execution of the MAT MERGE statement and the current element position for row 1 in work-vector-1, W1$\$(1)$, must be reset to hex(01). Since there are no more data to fill the row, however, the current element position for the row will remain hex(FF). When MAT MERGE is again executed, the row will be ignored.

The third merge pass will also terminate because of the emptying of a merge-array row (row 2). During this pass the locator-array will receive another element which is then moved to the output buffer. L$(\cdot)$ and W1$\$(\cdot)$ will thus contain:

\[
L$(\cdot)$ = \begin{array}{cccc}
0206 & 0000
\end{array} \\
(Q)
\]

\[
W1$\$(\cdot)$ = \begin{array}{cccc}
FF & FF & 06 & 02
\end{array}
\]

The fourth merge pass will now occur. L$(\cdot)$ will receive one element during this merge pass. L$(\cdot)$ and W1$\$(\cdot)$ will thus contain:

\[
L$(\cdot)$ = \begin{array}{cccc}
0306 & 0000
\end{array} \\
(R)
\]

\[
W1$\$(\cdot)$ = \begin{array}{cccc}
FF & FF & FF & 03
\end{array}
\]

The fourth merge pass also terminates because a row of the merge-array was emptied (row 3). This pass also terminates the merge phase, however because all elements of the merge-array have been exhausted. The last record is moved from the locator-array to the output buffer and execution of the merge phase terminates.
MAT MOVE

General Form:

MAT MOVE has two general forms:

MAT MOVE source-alpha-array [(s,n)], starting-locator-array-element ([,m]) TO starting-output-alpha-array-element ([,m])

and

MAT MOVE source-numeric-array, starting locator-array-element ([,m]) TO output-numeric-array-element ([,m])

Where:  (s,n) are expressions designating a field within each element of the source-alpha-array.

s specifies the starting position of the field (0 < s < bytes in the array).

n specifies the number of bytes in the field (0 < n < bytes in the array - s+1).

m is a numeric scalar variable specifying the maximum number of elements to be moved (0 < m < 32767).

Purpose:

MAT MOVE transfers data element-by-element from one array to another in the order specified by the subscript locator-array. Source and output-arrays can either be alphanumeric or numeric; however, both arrays must be the same type.

Data is transferred into sequential bytes in the output-alpha-array, row by row. If the move-array and receiver-array are alphanumeric, data may be transferred between specified fields of each element. MAT MOVE continues to transfer data until:

1. an element whose value is (hex (0000)) is found in the locator-array,
2. the end of the locator-array is reached,
3. m elements have been moved, or
4. the output-array has been filled.
The locator-array row/column subscripts point to the data in the source array which are to be moved to the output-array. The first subscript moved is the element specified as the starting-locator-array-element. The first element in the output-array to receive data is specified as the starting-output-array-element. Data are moved sequentially, row-by-row, from that point on. If the field expressions (s,n) are given, only data in the specified field of each element of the source-array are moved. For example, the statement

```
MAT MOVE A$(2,3), L$(1) TO B$(1)
```

specifies that only three bytes (the second, third and fourth) from each element of A$( ) are to be moved. If elements in the source-array contain fewer bytes than the elements in the output array, values are padded with spaces at the right. If elements in the source-array contain more bytes than the output-array-elements, they are truncated on the right.

When MAT MOVE has finished moving data, a count of the number of elements moved is returned to the variable m, if m has been specified.

Examples of valid syntax:

```
DIM A$(10,50), L$(50), A1$(100), A2$(50), A(10,50)
MAT MOVE A$( ), L$(1) TO A1$(1)
MAT MOVE A$( ), L$(10), G TO A2$(25)
MAT MOVE A$(3,2), L$(1) TO A2$(1)
```

Example 8: MAT MOVE

Given an array of data called A$( ) and an associated locator-array called L$( ), the following statements move the elements of A$( ) to the output array B$( ) in the order specified by the locator-array L$( ).

<table>
<thead>
<tr>
<th>row/col</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td>A$( )</td>
<td>F</td>
<td>A</td>
<td>G</td>
<td>I</td>
</tr>
<tr>
<td></td>
<td>H</td>
<td>E</td>
<td>J</td>
<td>D</td>
</tr>
<tr>
<td></td>
<td>C</td>
<td>L</td>
<td>B</td>
<td>K</td>
</tr>
</tbody>
</table>

```
L$( ) =

<table>
<thead>
<tr>
<th></th>
<th>0303</th>
<th>0301</th>
<th>0204</th>
</tr>
</thead>
<tbody>
<tr>
<td>(A)</td>
<td>(B)</td>
<td>(C)</td>
<td>(D)</td>
</tr>
<tr>
<td></td>
<td>0101</td>
<td>0103</td>
<td>0201</td>
</tr>
<tr>
<td>(E)</td>
<td>(F)</td>
<td>(G)</td>
<td>(H)</td>
</tr>
<tr>
<td></td>
<td>0104</td>
<td>0203</td>
<td>0304</td>
</tr>
<tr>
<td>(I)</td>
<td>(J)</td>
<td>(K)</td>
<td>(L)</td>
</tr>
<tr>
<td></td>
<td>0302</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
```
The locator-array provides the order in which data from the source-array is to be moved. L$(1,1) = 0102$ means "move the element in row 1, column 2 of A$()$ first", L$(1,2) = 0303$ means "move the element in row 3, column 3 next", etc. Subscripts in the locator-array appear in hexadecimal notation; letters in parentheses are the corresponding elements from A$()$. This example assumes that L$(1,1)$ was specified as the starting-locator-array-element.

When the following statements are executed

10 DIM A$(3,4)$1,L$(3,4)$2,B$(3,4)$1
20 MAT MOVE A$(())$,L$(1,1)$ TO B$(1,1)$

the array B$(())$ is created as:

<table>
<thead>
<tr>
<th></th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
</tr>
</thead>
<tbody>
<tr>
<td>E</td>
<td>F</td>
<td>G</td>
<td>H</td>
<td></td>
</tr>
<tr>
<td>I</td>
<td>J</td>
<td>K</td>
<td>L</td>
<td></td>
</tr>
</tbody>
</table>

This is the output-array after execution of MAT MOVE, assuming that B$(1,1)$ was specified as the starting-output-array-element.
MAT SEARCH

General Form:

\[
\text{MAT SEARCH search-alpha-array-designator} [\langle s, n \rangle], \{ \langle \rangle \} \text{ alpha variable TO location-array-designator [STEP expression]}
\]

Where:

(s, n) are expressions defining a field within the search-array.

s specifies the starting position determined by counting bytes left-to-right across the first row, left-to-right across the next row, and so on, ignoring element boundaries. \((0 \leq s \leq \text{bytes in the search-array})\).

n is the number of bytes to be searched. \((0 \leq n \leq \text{bytes in the search-array} - s + 1)\).

The STEP expression specifies that only substrings starting at every \(i\)th byte (where \(i = \text{value of the STEP expression}\)) are to be checked. The STEP expression must be \(0 < \text{expression} \leq 255\).

The location-array can have a minimum of one element. The length of each element must be two bytes.

Purpose:

MAT SEARCH scans the search-array for substrings that exactly or partially satisfy some specified relation and stores the location of each such substring in the location-array. The locations are stored as two-byte binary values in the order in which they are found, giving the location of the substring from the beginning of the search-array (or specified portion of the search-array). A portion of the search-array can be scanned by using the field limiting expressions (s, n). If these expressions are omitted, the entire array is scanned, starting with the first element. The search-array is treated as a single contiguous character string, i.e., element boundaries are ignored. The length of the substrings scanned in the search-array equals the length of the value of the alpha-variable with which they are compared.

NOTE:

If it is necessary to check for trailing spaces (hex(20)) or find an exact match, use the STR() function to specify the exact number of characters to check, e.g., MAT SEARCH A$(\cdot)$, = STR(Z$,1,5$) TO B$(\cdot)$ specifies a search for five-character substrings in A$(\cdot)$ which exactly equal the first five characters of Z$, including any trailing spaces. The STR() function ensures that trailing spaces are included in the value of Z$.
If the location-array is too small to accept all positions of the subtrings satisfying the given relation, the search terminates when the location-array is full. If there is space remaining in the location-array after the search is complete, the next element in the location-array is filled with zero (hex(0000)).

If the STEP parameter is not used, a step of one byte is implied. The search-array is treated as a contiguous byte string. MAT SEARCH starts at the first character in the search-array and checks to see if the character string starting with that character satisfies the given relation. If so, the location of the string is stored as the first element of the location-array. Then the substring starting at the second character is checked, and so on. If the STEP parameter is used, the position of the next substring to be checked is the starting position of the last substring checked plus the STEP expression. The search terminates when the number of characters remaining to be checked in the search-array is less than the length of the value of the variable being compared.

Consider a data file A$(i)$ containing the names of the 50 states blocked such that each 14 bytes represents a state name (STEP 14). The Search key is B$, the location-array designator is C$(i)($.)

CASE #1 - The exact match B$ = "MISSISSIPPI"
MAT SEARCH A$(i)$, = STR (B$,1) TO C$(i)$ STEP 14
Returns the location of MISSISSIPPI in the file.

CASE #2 - The partial match B$ = "MISS"
MAT SEARCH A$(i)$, = B$ TO C$(i)$ STEP 14
Returns the location of MISSISSIPPI and MISSOURI in the file.

CASE #3 - Any match B$ = "ISS"
MAT SEARCH A$(i)$, = B$ TO C$(i)$
Returns the positions of the first and second "ISS" in MISSISSIPPI and the position of MISSOURI.

NOTE:

The binary values in the location-array produced by MAT SEARCH are byte locations, not element subscripts. The first byte in the array area to be searched is byte 0001, the second byte is 0002, the third byte is 0003, etc. The MAT SEARCH location-array cannot be used by MAT MOVE, unless these byte locations are first converted to subscripts.
Examples of valid syntax:

MAT SEARCH A$( ), = B$ TO L$( )
MAT SEARCH A$( ), < Z$ TO L1$( )
MAT SEARCH A$( ), < R$ TO S1$( ) STEP 4
MAT SEARCH A$( ), < S, N$>, > STR(Q$,3,5) TO S$( )

Example 9: MAT SEARCH

Given array A$( ) as follows:

row/col =   1  2  3  4

<table>
<thead>
<tr>
<th></th>
<th>B</th>
<th>A</th>
<th>C</th>
<th>D</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>C</td>
<td>B</td>
<td>E</td>
<td>A</td>
</tr>
<tr>
<td>3</td>
<td>A</td>
<td>F</td>
<td>A</td>
<td>E</td>
</tr>
</tbody>
</table>

and a location-array B$( ) dimensioned B$(12)2, when the statements

20  INIT (FF) B$( ) : 0$="A"
30  MAT SEARCH A$( ), =0$ TO B$( )

are executed, the array B$( ) receives the locations of the character "A" in array A$( )]. These locations are counted from the first element specified, across each row left to right and stored as binary values. A binary zero is stored after the last location stored in B$( )]. B$( ) will contain:

row/col 1 2 3 4 5 6 ...... 12

<table>
<thead>
<tr>
<th></th>
<th>0002</th>
<th>0008</th>
<th>0009</th>
<th>000B</th>
<th>0000</th>
<th>FFFF</th>
<th>FFFF</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

If desired, the two-byte binary values in the location-array can be converted to decimal form and assigned to a numeric variable by a statement such as:

D = 256*VAL(B$(J)) + VAL(STR(B$(J),2))

where:

B$( ) is the location-array.
J is the subscript of the location-array element to be converted.
D is the numeric equivalent of the two-byte binary location.
Or, if desired, the binary location-array elements of \( B() \) could be converted to a set of subscripts which define the position of the search strings in the original search-array. This would allow the data which was searched for to be moved with MAT MOVE to another output file with a routine such as:

```
10 DIM A1$(124): REM LOCATOR-ARRAY FOR MAT MOVE
20 INIT ("O") A1$( )
30 INPUT "STARTING ELEMENT IS", S
40 INPUT "ENDING ELEMENT IS", N
50 I = 1
60 IF B$(I) = HEX (0000) THEN 110
70 CONVERT INT ((S-2+VAL(STR(B$(I),2)))/4)+1 TO STR(A1$(I),1,2),(#)
80 CONVERT VAL(STR(B$(I), 2))+S-1-(INT((S-2+VAL(STR(B$(I),2))/4#))
TO STR(A1$(I), 3, 2),(#)
90 I = I+1
100 GO TO 60
110 MAT PRINT A1$; :REM A1$( ) contains the subscript pointers to the
locations of the search strings in the original search-array
```

:RUN
0102
0204
0301
0303
0000

...
MAT SORT

General Form:

MAT SORT sort-array TO work-array, locator-array

Where: The work-array and the locator-array have at least as many elements as the sort-array. The elements in these arrays must be of length=2.

The sort-array cannot contain more than 4096 elements.

Purpose:

MAT SORT takes the elements of the sort-array and creates an output locator array of their subscripts arranged according to the ascending order of the elements in the sort-array. Subscripts are stored in the locator-array as two-byte values; the first byte is the row subscript, the second byte is the column subscript. If the locator-array contains more elements than the sort-array \( n \), then the \( n+1 \) element of the locator-array contains zero (hex(0000)).

MAT MOVE uses the locator-array to create a new data array in sorted order.

NOTE:

The subscripts of sort-array elements of identical value are stored contiguously in the locator-array, but they are not necessarily ordered as in the sort-array.
Example of valid syntax:

MAT SORT A$() TO W$(), L$()

<table>
<thead>
<tr>
<th>row/col</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>C</td>
<td>A</td>
<td>E</td>
<td>I</td>
</tr>
<tr>
<td>2</td>
<td>L</td>
<td>J</td>
<td>G</td>
<td>B</td>
</tr>
<tr>
<td>3</td>
<td>H</td>
<td>D</td>
<td>K</td>
<td>E</td>
</tr>
</tbody>
</table>

If G$() =

The following statements take a sort-array of twelve elements, G$(), and create a subscript array G1$().

10 DIM G$(3,4)1, W$(3,4)2, G1$(3,4)2
20 MAT SORT G$() TO W$(), G1$()

G1$()=

<table>
<thead>
<tr>
<th></th>
<th>0102</th>
<th>0204</th>
<th>0101</th>
<th>0302</th>
</tr>
</thead>
<tbody>
<tr>
<td>0304</td>
<td>0103</td>
<td>0203</td>
<td>0301</td>
<td></td>
</tr>
<tr>
<td>0104</td>
<td>0202</td>
<td>0303</td>
<td>0201</td>
<td></td>
</tr>
</tbody>
</table>

Thus, the lowest value is in element (1,2), i.e., the letter A in row 1, column 2; the second lowest value is in element (2,4), i.e., the letter B in row 2, column 4, etc.

NOTE:

Every byte of an alphanumeric array in the System 2200 is set to all blank characters (HEX(20)) when initially defined unless explicitly set to some other character with an INIT statement. Since HEX(20) is lower in the collating (sorting) sequence than other standard characters, HEX(20)'s will always float to the top (beginning) of any sorted array. It is therefore good practice to initialize arrays to be sorted with an INIT(FF) statement. This will ensure that the unused elements of any array will sink to the bottom (end) of the sorted array.
Example 10: Using MAT SORT and MAT MOVE

In the following short program, an input or sort array, I$(())$, is processed by MAT SORT which fills the locator-array L$(())$ containing the subscript pointers. Then the locator-array is used by MAT MOVE to pick off the elements of the sort-array in sorted order and place them in the sorted output-array, O$(())$.

10 DIM I$(10)1, W$(10)2, L$(12)2, O$(10)1
20 FOR I=1 TO 10 : INPUT I$(I) : NEXT I
30 MAT SORT I$(()) TO W$(()), L$(())
40 FOR I=1 TO 12 : HEXPRINT L$(I) : NEXT I
50 M=10
60 PRINT
70 MAT MOVE I$(()), L$(1), M TO O$(1)
80 FOR I=1 TO 10 : PRINT O$(I) : NEXT I

Input up to ten single letter array elements (not in alphabetical order). The locator-array is printed in hex-codes; the output-array is printed as usual.

:RUN (EXEC)
? S, D, E, A, Z, X, Y, G, B, J (EXEC)
040109010201030108010A01010106010701050100002020
ABCDEGJSXYZ

Figure 1-8. Output from Example 1
APPENDIX A: ERROR CODES

Code: =1
Error: MISSING NUMERIC ARRAY DESIGNATOR
Cause: A numeric array designator (e.g., N()) was expected.
Action: Correct the statement in errcr.
Example: 100 MAT CONVERT A$(,) TO N()
          \[ERR=1\]
          100 MAT CONVERT N() TO A$(,)
          (Possible Correction)

Code: =2
Error: ARRAY TOO LARGE
Cause: The specified array contains too many elements. For example, the
        number of elements cannot exceed 4096.
Action: Correct the program.
Example: 10 DIM A$(100,50)2, B$(100,50)2, W$(100,50)2
        .
        .
        100 MAT SORT A$(,) TO S$(,), B$(,)
        \[ERR=2\]
        10 DIM A$(100,40)2, B$(100,40)2, W$(100,40)2
        (Possible Correction)

Code: =3
Error: ILLEGAL DIMENSIONS
Cause: The defined dimensions or element length of the array are illegal.
Action: Dimension the array properly.
Example: 10 DIM A$(63), B$(63)1, W$(63)2
        .
        .
        100 MAT SORT A$(,) TO W$(,), B$(,)
        \[ERR=3\]
        10 DIM A$(63), B$(63)2, W$(63)2
        (Possible Correction)
APPENDIX B: MAT SORT/MAT MERGE TIMING

The timing characteristics of the algorithms chosen to implement MAT SORT should be considered when planning sorting applications. The speed with which data are sorted depends upon the number of passes made through the data, the amount of work done on each pass to reduce the data to sorted order and the characteristics of the data. It is a feature of the MAT SORT algorithm that judicious choice of array size and dimensions can produce marked improvements in execution time for sorting operations. The program in Appendix E is provided for this purpose.

Execution time for MAT SORT is generally proportional to the expression:

\[ n(\log_2 n)^2 \]

where \( n \) is the number of elements in the array to be sorted. The worst results occur when \( n \) is a power of two (i.e., \( n=2^x \)); and the best results occur when \( n=(2^x+1) \). (See Table and Figure B-1). As \( n \) increases, substantial improvements in overall sorting time can be achieved by separating the elements to be sorted into groups, sorting within each group and then using MAT MERGE to merge the groups.

While each additional row of data added to the merge array causes a linear increase in the time required for sorting when using both MAT SORT and MAT MERGE, (see Table and Figure B.2), this bookkeeping time reduces the potentially exponential effect of the necessary across-row comparisons. Therefore, the user is advised to choose a constant row size to correspond to one of the optimal cases in the MAT SORT routine. A good choice might be 129 elements in a row since 128 is the largest power of two less than 255, the maximum row length.

While these characteristics of MAT SORT and MAT MERGE can be of value to the experienced user, it is most likely that setup time for large arrays will greatly exceed actual sorting time. To aid in minimizing setup time, MAT MOVE and MAT COPY should be used for their ability to move large volumes of data rapidly within memory. The greatest total sort speeds will be exhibited by BASIC programs which utilize all the Sort ROM commands effectively.

The tables and graphs illustrating MAT SORT/MAT MERGE timing for several array sizes have been empirically determined; dots are actual times as given in the tables.
Table B-1. MAT SORT Timing

<table>
<thead>
<tr>
<th>Number of Elements</th>
<th>Time (in seconds)</th>
</tr>
</thead>
<tbody>
<tr>
<td>100</td>
<td>0.66</td>
</tr>
<tr>
<td>128*</td>
<td>1.20</td>
</tr>
<tr>
<td>129</td>
<td>0.98</td>
</tr>
<tr>
<td>200</td>
<td>1.68</td>
</tr>
<tr>
<td>256*</td>
<td>3.80</td>
</tr>
<tr>
<td>258</td>
<td>2.30</td>
</tr>
<tr>
<td>300</td>
<td>2.95</td>
</tr>
<tr>
<td>400</td>
<td>4.60</td>
</tr>
<tr>
<td>500</td>
<td>7.20</td>
</tr>
<tr>
<td>510</td>
<td>10.20</td>
</tr>
<tr>
<td>512*</td>
<td>11.00</td>
</tr>
<tr>
<td>513</td>
<td>6.20</td>
</tr>
<tr>
<td>600</td>
<td>7.80</td>
</tr>
<tr>
<td>800</td>
<td>12.00</td>
</tr>
<tr>
<td>1000</td>
<td>18.00</td>
</tr>
<tr>
<td>1024*</td>
<td>30.90</td>
</tr>
<tr>
<td>1025</td>
<td>15.50</td>
</tr>
<tr>
<td>2000</td>
<td>43.00</td>
</tr>
</tbody>
</table>

*Powers of 2

Figure B-1. MAT SORT Timing
Table B-2. MAT SORT/MAT MERGE Timing

<table>
<thead>
<tr>
<th>Number of Elements</th>
<th>Time (in seconds)</th>
</tr>
</thead>
<tbody>
<tr>
<td>500 (5 x 100)</td>
<td>4.6</td>
</tr>
<tr>
<td>645 (5 x 129)</td>
<td>6.0</td>
</tr>
<tr>
<td>774 (6 x 129)</td>
<td>7.0</td>
</tr>
<tr>
<td>903 (7 x 129)</td>
<td>9.0</td>
</tr>
<tr>
<td>1032 (8 x 129)</td>
<td>10.0</td>
</tr>
<tr>
<td>1161 (9 x 129)</td>
<td>11.0</td>
</tr>
<tr>
<td>1290 (10 x 129)</td>
<td>13.0</td>
</tr>
<tr>
<td>2000 (20 x 100)</td>
<td>22.0</td>
</tr>
</tbody>
</table>

Figure B-2. MAT SORT/MAT MERGE Timing
APPENDIX C: SOME USEFUL DEFINITIONS

array: a number of related elements arranged in a specified order. Arrays can be one- or two-dimensional. A one-dimensional array has one row and is sometimes called a vector; a two-dimensional array has both rows and columns.

byte: a sequence of adjacent binary digits (bits) operated on as a unit; one byte contains eight bits.

field: a set of bytes within a record (or array) specified for use by a particular category of data.

key: one or more characters or fields within a record that are used to identify it or control its use.

locate mode: a means of accessing data by pointing to its location instead of moving it.

merge: to combine items from two or more similarly ordered sets into a single set that is arranged in the same order.

pointer: an address or other indication of location.

record: a collection of related items of data treated as a unit (for example, one line of an invoice may form a record; one item in the line such as quantity is a field).

sort: to segregate items into groups according to some rule or rules.

string: A subfile of records stored in sorted order.

subscript: an identifying character or number written below and to the right of another character. In Sort statements, the locator-arrays contain subscripts of alpha-array elements.

vector: a one-dimensional array.

work array: an intermediate array used for temporary storage of data between phases.
APPENDIX D: ASCII, HEX, Binary and Decimal (VAL) Equivalents Table

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APPENDIX E: APPROXIMATING THE PARAMETERS FOR SORT/MERGE

This program is designed to approximate the optimal sizes of the Sort, Merge, Locator, Work and Output arrays for a given memory capacity, input file and Sort key length.

10 REM PRG DETERMINES SIZES OF COMPONENTS FOR SORT/MERGE-2200T
20 REM CRT/PRINTER INDICATOR
30 DIM C1X
40 REM ROUND UP ROUTINE
50 DEFINT I$1=INT(X$+.999999999999)
60 SELECT PRINT 00546
70 PRINT HEX(6):"PROGRAM TO DETERMINE SIZES OF COMPONENTS FOR SORT/MERGE (2200T):HEX(6A)
80 INPUT 'MEMORY SIZE (K)'#1,
90 INPUT 'MAXIMUM NUMBER OF RECORDS',N
100 INPUT 'NUMBER OF RECORDS PER SECTOR',B
110 REM MAXIMUM SIZE SORT KEY = 60 IF UNBLOCKED
120 K=60
130 IF B=1 THEN 160
140 REM MAXIMUM SIZE SORT KEY = 59 IF BLOCKED
150 K=59
160 PRINT 'LENGTH OF SORT KEY (MAX:K0;1)':
170 INPUT K
180 IF K<1 THEN 160
190 IF K>60 THEN 160
200 IF K<10 THEN 160
210 REM AVAILABLE MEMORY FOR EITHER SORT OR MERGE PHASE
220 K=K1*1024-698-1400
230 REM IF ONE RECORD PER SECTOR, ADDRESS POINTER IS 2 BYTES
240 K=2
250 REM 124 TWO BYTE ADDRESSES PER SECTOR IN TAG FILE
260 K=124
270 IF B=1 THEN 330
280 REM IF BLOCKED RECORDS, ADDRESS POINTER IS 3 BYTES
290 K=3
300 REM 80 THREE BYTE ADDRESSES PER SECTOR IN TAG FILE
310 K=80
320 REM TOTAL KEY/ADDRESS LENGTH
330 K=K+M1
340 REM NUMBER OF KEYS=ADDRESSES PER SECTOR, COLS IN SORT ARRAY
350 K=INT(253/K2+1))
360 REM MEMORY REQUIRED FOR SORT OUTPUT / MERGE INPUT BUFFER
370 K=K*2+3
380 REM MEMORY REQUIRED FOR MERGE OUTPUT BUFFER
390 K=K+M4+K5
400 REM ELEMENT SIZE OF DISK RECORD FOR MERGE OUTPUT (TAG) FILE
410 K=K1*5/4
420 REM NUMBER OF DIVISIONS OF ORIG FILE REQUIRED
430 D=FMU(FMU(K2-K4)/(K2+4))
440 REM MAXIMUM RECORDS PER DIVISION
450 K=K*FMU(K4/@D)/K3
460 REM TOTAL SECTORS REQUIRED FOR SORT OUTPUT FILE
470 F2=M2*K3
480 REM ABSOLUTE MAXIMUM NUMBER OF RECORDS
490 K=K2
500 REM TOTAL SECTORS REQUIRED FOR MAXIMUM INPUT FILE
510 F1=FMU(FM(U/@D))
520 REM ROWS IN SORT/WORK/LOCATOR ARRAYS
530 B=K2/K3
540 REM MEMORY REQUIRED BY SORT ARRAY
550 S=K*3M3*K2+2
560 REM MEMORY REQUIRED BY WORK ARRAY
570 S2=K*M3*P2+7
580 REM MEMORY REQUIRED BY SORT LOCATOR ARRAY
590 S3=K*3*K2+2
600 REM TOTAL MEMORY REQUIRED BY SORT/WORK/LOCATOR/OUTPUT
610 M=S1+S2+S3*K4+M4
620 REM COLUMNS REQUIRED FOR MERGE & MERGE LOCATOR ARRAY
630 X=INT(K2/@D)
640 IF X<255 THEN 460
650 X=255
660 X=3*K*INT(X/K3)
670 REM MEMORY REQUIRED BY MERGE ARRAY
680 T4=0M4*K2+7
690 REM MEMORY REQUIRED BY WORK ONE ARRAY
700 T4=0T4+17
710 REM MEMORY REQUIRED BY WORK TWO ARRAY
720 T3=0M2+27
730 REM MEMORY REQUIRED BY MERGE LOCATOR ARRAY
740 T4=0M4*K2+7
750 REM TO MEMORY REQUIRED BY MERGE/WORK1/WORK2/LOCATOR/OUTPUT
760 M5=K4*T4+T2+T3+T4+M6
770 REM MAXIMUM RECORDS IN TAG FILE
780 K3=FMU(FM(U/@D))
790 REM TOTAL SECTORS REQUIRED FOR MERGE OUTPUT (TAG) FILE
800 F3=M3*K5+2
810 INPUT "ENTER 1 FOR CRT, 2 FOR PRINTER, 3 TO STOP, Z"
820 IF X=1 THEN 860
830 IF X=2 THEN 890
840 IF X=3 THEN 1450
850 GOTO 810
860 SELECT PRINT 005(44)
870 C3=HEX(63)
880 GOTO 910
890 SELECT PRINT 215(44)
900 C3=HEX(6A)

45
16 K SYSTEM
SYSTEM OVERHEAD (22007) -698
SORT OR MERGE PROGRAM -1400
MET MEMORY AVAILABLE 14286

INPUT FILE
MAX RECORDS (1000) 1008
NO. REC PER SECTOR 1
TOT NO. SECTORS 1010

SORT KEY
SORT KEY LENGTH 31
ADDRESS POINTER 2
TOT KEY/ADD LENGTH 33

SORT PHASE
SORT ARRAY S1(48 , 7 ) 33 11095
WORK ARRAY L4(48 , 7 ) 2 679
LOCATOR ARRAY L4(48 , 7 ) 2 679
OUTPUT BUFFER D4(7) 33 238
TOTAL MEMORY 12691

OUTPUT FILES
NUMBER NEEDED 3
MAX. RECORDS 334
RECORDS/SECTOR 7
TOT SECT/FILE 50

MERGE PHASE
INPUT BUFFER L4(7) 33 238
MERGE ARRAY L4(3,112)33 11095
WORK ARRAY 1 L1(4) 1 11
WORK ARRAY 2 L1(3) 2 13
LOCATOR ARRAY L4(3,112) 2 679
OUTPUT BUFFER D4(124) 2 256
TOTAL 12291

OUTPUT FILE
MAX RECORDS 1116
RECORDS/SECTOR 124
TOT SECTORS 11
NOTE: MERGE OUTPUT BUFFER AND OUTPUT TAG FILE
DIMENSIONED IN MEMORY AS D4(124 ) 2
RECORDS STORED ON DISK AS D4( 4 ) 62

...
APPENDIX F: EXTERNAL SORT/MERGE EXAMPLE

This program is designed to demonstrate a common external sorting technique.

--- PROGRAM DESCRIPTIONS ---

SRTMRC10 - RESERVE SPACE
RESERVES SPACE FOR THE DATA FILES REQUIRED FOR THE SORT - MERGE EXAMPLE.

SRTMRC20 - CREATE DATFILE1
USES THE RANDOM NUMBER GENERATOR TO CREATE 90 SIX DIGIT NUMBERS
THEY ARE BLODDED 10 PER SECTOR AND STORED AS ALPHANUMERIC CHARACTERS, I.E. 6814016. THEY ARE WRITTEN TO DATFILE1.

SRTMRC30 - PRINT FILE
PRINTS THE CONTENTS OF THE DATA FILES USED BY THE SORT - MERGE EXAMPLE. THE NAME OF THE FILE IS ENTERED BY THE OPERATOR.

SRTMRC40 - SORT
READS IN DATFILE1 IN THREE GROUPS, SORTS EACH GROUP AND WRITES EACH GROUP TO SEPARATE FILES (DATFILE2, DATFILE3, & DATFILE4).

SRTMRC50 - MERGE
MERGES THE THREE SORTED FILES (DATFILE2, DATFILE3, & DATFILE4) INTO ONE FILE (DATFILE5).

--- DATA FILE DESCRIPTIONS ---

DATFILE1
THE ORIGINAL DATA IN RANDOM ORDER. 11 SECTORS RESERVED. NINE
LOGICAL RECORDS OF 1 SECTOR EACH. EACH LOGICAL RECORD CONTAINS
10 6-DIGIT NUMBERS STORED AS 6 ALPHANUMERIC CHARACTERS.

DATFILE2, DATFILE3, & DATFILE4
EACH FILE CONTAINS ONE-THIRD OF THE ORIGINAL DATA SORTED IN
ASCENDING SEQUENCE. 5 SECTORS RESERVED FOR EACH FILE. LOGICAL
RECORDS ARE THE SAME AS DATFILE1

DATFILE5
ORIGINAL DATA SORTED IN ASCENDING SEQUENCE. SAME DESCRIPTION
AS DATFILE1.
10 REM PROGRAM NAME = "SRTNRG10"
20 REM THIS PROGRAM RESERVES SPACE ON DISK FOR THE DATA FILES
30 REM FOR THE SORT-MERGE EXAMPLE
40 SELECT 01 310
50 SELECT PRINT 005(44)
60 PRINT HEX(03):"PROCESSING SRTNRG10"
70 PRINT "ALLOCATING SPACE FOR THE FIVE DATAFILES"
80 DATA SAVE DC OPEN T81, 11, "DATFILE1"
90 DATA SAVE DC #1, END
100 DATA SAVE DC OPEN T81, 5, "DATFILE2"
110 DATA SAVE DC #1, END
120 DATA SAVE DC OPEN T81, 5, "DATFILE3"
130 DATA SAVE DC #1, END
140 DATA SAVE DC OPEN T81, 5, "DATFILE4"
150 DATA SAVE DC #1, END
160 DATA SAVE DC OPEN T81, 11, "DATFILES"
170 DATA SAVE DC #1, END
180 DATA SAVE DC CLOSE ALL
190 STOP "- SPACE ALLOCATED"

10 REM PROGRAM NAME = "SRTNRG20"
20 REM THIS PROGRAM CReATES THE DATA FOR "DATFILE1" VIA THE
30 REM RANDOM NUMBER GENERATOR
40 SELECT 01 310
50 SELECT PRINT 005(44)
60 PRINT HEX(03):"PROCESSING SRTNRG20"
70 PRINT "CREATING DATFILE1"
80 DIM A$1016
90 DATA LOAD DC OPEN T81, "DATFILE1"
100 FOR I=1 TO Y
110 FOR J=1 TO 10
120 X=RND(I)
130 X=X*1000000 TO A$1(J), (000000)
140 NEXT J
150 DATA SAVE DC #1, A$(1)
160 NEXT I
170 DATA SAVE DC #1, END
180 DATA SAVE DC CLOSE ALL
190 STOP "- DATFILE1 CREATED"

10 REM PROGRAM NAME = "SRTNRG30"
20 REM THIS PROGRAM PRINTS THE CONTENTS OF THE DATA FILES USED
30 REM IN THE SORT-MERGE EXAMPLE. FILE NAME IS ENTERED.
40 SELECT 01 310
50 SELECT PRINT 005(44)
60 PRINT HEX(03):"PROCESSING SRTNRG30"
70 PRINT "PRINTS THE CONTENTS OF DATFILE1, DATFILE2, DATFILE3, DATFILE4,"
80 PRINT "OF DATFILES"
90 DIM A$1016,F90
100 INPUT "NAME OF FILE TO BE PRINTED",F90
110 DATA LOAD DC OPEN T81, F90
120 SELECT PRINT 215(132)
130 PRINT HEX(0D)(0C)(0A)(0A)
140 PRINT HEX(0A)(0A)
150 M=0
160 DATA LOAD DC #1, A$(1)
170 IF END THEN 240
180 M=M+1
190 PRINT M;
200 FOR I=1 TO 10
210 PRINT TAB(8*I);A$(I);
220 NEXT I
230 PRINT
240 PRINT HEX(0A)(0A)
250 DATA SAVE DC CLOSE ALL
270 PRINT HEX(0D)
280 SELECT PRINT 005(44)
290 STOP "- FILE PRINTED"
10 REM PROGRAM NAME = "SRTHRG40"
20 REM THIS PROGRAM READS IN "DATFILE1" AND CREATES 3 SORTED
30 REM SUBFILES - "DATFILE2", "DATFILE3", & "DATFILE4"
40 SELECT #1, 310, #2 310
50 SELECT PRINT 005(44)
60 PRINT HEX(03):"PROCESSING SRTHRG40"
70 PRINT CREATING SORTED SUBFILES DATFILE2, DATFILE3, DATFILE4 FROM "DATFILE1"
80 PRINT "DATFILE1"
90 DIM A(A10),S(10),T(10),W(30),L(30),F(8)
100 F#="DATFILE1"
110 DATA LOAD DC OPEN TH1, F#: REM OPEN INPUT FILE
120 SELECT PRINT 215 (132): PRINT HEX(1C)
130 FOR J=1 TO 3: REM DIVIDE FILE INTO THIRDS
140 PRINT HEX(00):"GROUP #"J
150 FOR K=1 TO 3: REM EACH THIRD CONTAINS 3 RECORDS OF 10 RECORDS
160 DATA LOAD DC R#,A(): REM READ RECORD
170 COSUB 390: REM PRINT CONTENTS OF INPUT BUFFER
180 MAT COPY A() TO R(K): REM TRANSFER INPUT BUFFER TO SORT ARRAY
190 NEXT J
200 H=0: FOR J=1 TO 21: H=H+1: REM MOVE 1 TO A TIME TO OUTPUT BUFFER AND SAVE
210 FOR J=1 TO 21: REM WRITE RECORD
220 NEXT J
230 REM WRITE GROUP OF 10
240 DATA SAVE DC R#, A(): REM WRITE RECORD
250 NEXT J: REM NEXT GROUP OF 10
260 DATA SAVE DC R#, END: END: REM WRITE ED
270 DATA SAVE DC DC, END: REM WRITE ED
280 DATA SAVE DC DC, END: REM CLOSE OUTPUT WORK FILE
290 PRINT HEX(00000)
300 NEXT I: REM NEXT THIRD
310 DATA SAVE DC DC, END: REM CLOSE ALL FILES
320 DATA SAVE DC DC, END: REM WRITE ED
330 PRINT HEX(0C)
340 SELECT PRINT 005(44)
350 STOP "_creator created"
360 REM PRINT CONTENTS OF A() ON ONE LINE
370 FOR K=1 TO 10:PRINT TAB(10*(K-1));A(K):NEXT K:PRINT :RETURN

10 REM PROGRAM NAME = "SRTHRG50"
20 REM MERGES DATFILE2, DATFILE3, & DATFILE4 INTO DATFILES
30 REM SELECT PRINT 005(44):PRINT HEX(03):"PROCESSING SRTHRG50"
40 SELECT #1, 310, #2 310, #3 310, #4 310, #5 310, #6 310, #7 310, #8 310,...
50 DIM M(3,10),S(10),T(10),W(10),L(10),F(8),W(30),L(30)
60 REM OPEN INPUT WORK FILES
70 DATA LOAD DC OPEN TH1, "DATFILE2"
80 DATA LOAD DC OPEN TH2, "DATFILE3"
90 DATA LOAD DC OPEN TH3, "DATFILE4"
100 REM OPEN OUTPUT FILE
110 DATA LOAD DC OPEN TH4, "DATFILE1"
120 PRINT HEX(0C)
130 GOTO 220
140 DEFF "40"(R): REM SUBROUTINE TO FILL ROW "R"
150 PRINT "": FILL ROW:"R"
160 DATA LOAD DC #R, 186: REM READ RECORD FROM FILE R
170 IF END THEN 200: REM IF EOF LEAVE ISM POINTER AT HEX(FF)
180 MAT COPY I() TO M(H): REM TRANSFER TO ROW R
190 W(186)=HEX(01): REM RESET ROW POINTER TO COLUMN ONE
200 W(186)=HEX(00): REM RESETS TERMINATION INDICATOR
210 RETURN
220 FOR I=1 TO 3: REM PRINT ALL THREE ROWS INITIALLY
230 COSUB '401T'
240 PRINT
250 NEXT T
260 M=1: REM SET LOCATION IN OUTPUT BUFFER TO ONE
270 X=1: REM SET # MESSAGES TO ZERO
280 INIT(000) S#: REM CLEAR S# MESSAGE ARRAY TO ZEROS
290 PRINT "": W(186)="":FOR I=1 TO 4:PRINT W(186):PRINT "":NEXT I:PRINT
300 REM MESSAGE M(H) TO W(H), T(H), W(H), S#: REM OBTAIN MESSAGES FOR ROW
310 X=X+1: REM UPDATE # MESSAGE COLORS
320 PRINTING 570,4:FOR I=1 TO 20:PRINT "":NEXT I:PRINT
330 IF W(186)=HEX(FF) THEN 520: REM IF TRUE WE ARE DONE
340 S=1: REM SET LOCATION IN SUBFILES ARRAY TO ONE
350 M=10: REM MAXIMUM TO MOVE IS TEN
360 REM MOVE M(H), S(H), TO D(M): REM MOVE TO OUTPUT BUFFER
370 PRINTING 580,4:FOR I=1 TO 10:PRINT TAB(1*(I-1));D(M):NEXT I:PRINT
380 W(186)=HEX(00): REM UPDATE LOCATION IN OUTPUT BUFFER
390 IF M=10 THEN 460: REM IS OUTPUT BUFFER FULL?
400 DATA SAVE DC #M, 191: REM IF SO WRITE RECORD
410 PRINT "": "WRITE RECORD"
420 INIT(010H): REM RESCUE OUTPUT BUFFER TO EMPTY CONDITION
430 REM CLEAR THE MERGED LOCATION IN OUTPUT BUFFER TO ONE
440 S=1: REM UPDATE LOCATION IN SUBFILES ARRAY
450 IF X=20 THEN 350: REM HAVE WE MOVED ALL ELEMENTS THIS PASS?
460 PRINT
470 T=VAL(W(186)): REM DETERMINE WHICH MESSAGE TERMINATED
480 REM IF TERMINATED THEN 280: REM TERMINATE BECAUSE SUBSCRIPT ARRAY FULL, BACK TO MERGE
490 PRINT "": W(186)="":FOR I=1 TO 4:PRINT W(186):PRINT "":NEXT I:PRINT
500 COSUB '401T': REM TERMINATE BECAUSE EOF REACHED, REFILL
510 GOTO 280: REM BACK TO MERGE
520 DATA SAVE DC #M, END: REM END OF MERGE, WRITE ED
530 DATA SAVE DC DC, END: REM CLOSE ALL FILES
540 PRINT HEX(0C)
550 SELECT PRINT 005(44)
560 STOP "": END OF MERGE
570 T=# MERGE S(4)"
580 Z MOVED #99 --- 015 =
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APPENDIX G: INTERNAL SORT/SEARCH EXAMPLES

These programs exemplify and compare various internal sorting and searching techniques.

10 REM PROGRAM TO ILLUSTRATE THE USE OF MAT SORT AND THE THREE
20 REM FORMS OF MAT SEARCH: EXACT, PARTIAL, & ANY CHAR STRING
30 DIM S1(50), S2(50), A1(50), A2(50), W(50), L1(50), S1(50), S1(50)
40 RESTORE: MAT READ S1, A1: GOSUB 0: STOP * SELECT FUNCTION*
50 REM ............ FUNCTION LIST
60 DEF F0
70 PRINT HEX(03): "COMPARISON OF SORT ROM AND BASIC";
80 PRINT "THE DATA USED IS THE 50 STATES AND THEIR ABBREVIATIONS":HEX(0A)
90 PRINT "F1 KEY FUNCTION";
100 PRINT "F2 FUNCTION LIST";
110 PRINT "F3 ORIGINAL DATA";
120 PRINT "F4 SORT USING MAT SORT";
130 PRINT "F5 SEARCH USING MAT SEARCH- EXACT ENTRY")
140 PRINT "F6 SEARCH USING MAT SEARCH- PARTIAL ENTRY")
150 PRINT "F7 SEARCH USING MAT SEARCH- ANY CHARACTER STRING")
160 PRINT "F8 RETURN")
170 RETURN
180 REM ............ ORIGINAL DATA
190 RETURN
200 PRINT HEX(03): "ORIGINAL DATA")
210 FOR I=1 TO 50 : PRINT S1(I,1)) : NEXT I : RETURN
220 REM ............ SORT USING MAT SORT
230 DEF F2
240 PRINT HEX(03): "SORT WITH MAT SORT")
250 MAT SORT S1(1) TO W(I,1)
260 MAT MOVE S1(1), L1(1) TO W(2,1)
270 MAT MOVE A1(1), L1(2) TO W(2,1)
280 FOR I=1 TO 50 : PRINT S2(I,1)) : NEXT I : RETURN
290 REM ............ SEARCH USING MAT SEARCH- EXACT ENTRY
300 DEF F4
310 PRINT HEX(03): "SEARCH USING MAT SEARCH- EXACT ENTRY")
320 S=+ *
330 INPUT "STATE (EXEC IF DONE), $s")
340 IF S="O" THEN 560
350 PRINT "F4")
360 MAT SEARCH S1(1))=STR$(S,1)) TO L1(1) STEP 14
370 IF L1(1))HEX(0000) THEN 400
380 PRINT NOT ON FILE")
390 GOTO 320
400 X=2&4VAL(W(I,1))=VAL(S1(1,1,2)) : REN CONVERT BINARY TO DECIMAL
410 PRINT X))=1))HEX(1)) STEP 14 : REN CONVERT CHARACTER TO ARRAY ELEMENT (1-50)
420 PRINT Y, S1(1,1), A1(1,1)
430 GOTO 320
440 REM ............ SEARCH USING MAT SEARCH- PARTIAL ENTRY
450 DEF F4
460 PRINT HEX(03): "SEARCH USING MAT SEARCH- PARTIAL ENTRY")
470 PRINT S=+ *
480 S=+ *
490 INPUT "STATE (EXEC IF DONE), $s")
500 IF S="O" THEN 520
510 PRINT "F4")
520 MAT SEARCH S1(1), S$ TO L1(1) STEP 14
530 IF L1(1))HEX(0000) THEN 540
540 PRINT NOT ON FILE")
550 GOTO 470
560 I=1+
570 IF L1(1))HEX(0000) THEN 470
580 X=2&4VAL(W(I,1))=VAL(S1(1,1,2)) : REN CONVERT BINARY TO DECIMAL
590 Y=2&4VAL(W(I,1))=VAL(S1(1,1,2)) : REN CONVERT CHARACTER TO ARRAY ELEMENT (1-50)
600 PRINT Y, S1(1,1), A1(1,1)
610 I=1+
620 IF I<50 THEN 570
630 GOTO 470
640 REM ............ SEARCH USING MAT SEARCH- ANY CHAR STRING
650 DEF F4
660 PRINT HEX(03): "SEARCH USING MAT SEARCH- ANY CHAR STRING")
670 PRINT S=+ *
680 S=+ *
690 INPUT "CHARACTER STRING (EXEC IF DONE), $s")
700 IF S="O" THEN 720
710 RETURN
720 MAT SEARCH S1(1), S$ TO L1(1)
730 IF L1(1))HEX(0000) THEN 740
740 PRINT NOT ON FILE")
750 GOTO 470
760 I=1+
770 IF L1(1))HEX(0000) THEN 670
780 X=2&4VAL(W(I,1))=VAL(S1(1,1,2)) : REN CONVERT BINARY TO DECIMAL
790 Y=2&4VAL(W(I,1))=VAL(S1(1,1,2)) : REN CONVERT CHARACTER TO ARRAY ELEMENT (1-50)
800 Z=2&4VAL(W(I,1))=VAL(S1(1,1,2)) : REN CONVERT CHARACTERTO ARRAY ELEMENT (1-14)
810 PRINT "ELEMENT", Y, "CHAR LOC", Z, S1(1,1), A1(1,1)
820 I=1+
830 IF I<60 THEN 770
840 GOTO 470
850 DATA "HAWAII", "TENNESSEE", "VIRGINIA", "NEW YORK", "MAINE", "SOUTH DAKOTA", "SOUTH CAROLINA", "NEW HAMPSHIRE", "VERMONT", "INDIANA", "MISSISSIPPI", "DELAWARE", "ALABAMA", "GEORGIA", "NEW MEXICO"
880 DATA "COLORADO", "NORTH DAKOTA"
900 DATA "TI", "ME", "IL", "AR", "ND", "AZ", "HI", "KS", "CT", "MT", "CO", "ND"
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